



# Ethernet Test

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## *Experimenting with MikroE Libraries*

There is very little in the way of examples for using Mikroelektronika libraries for PIC32. This results in trial by error programming and a lot of hard work. The project represented here can serve as a skeleton for more complete development.

## *General*

Ethernet is one of the most popular interfaces in the microcontroller world. It is fast and can span long distances. It is the communications choice in small factories for interfacing tools and monitoring equipment.

The PIC32MX7 is ideally suited for this task with its built-in Ethernet controller. It has the right mix of serial interfaces and I/O for various applications in factory automation and process control.

## *Scope*

This project attempts to construct several applications for Ethernet which run simultaneously on the microprocessor. It is a starting point for further development in implementing real world products.

## *Method*

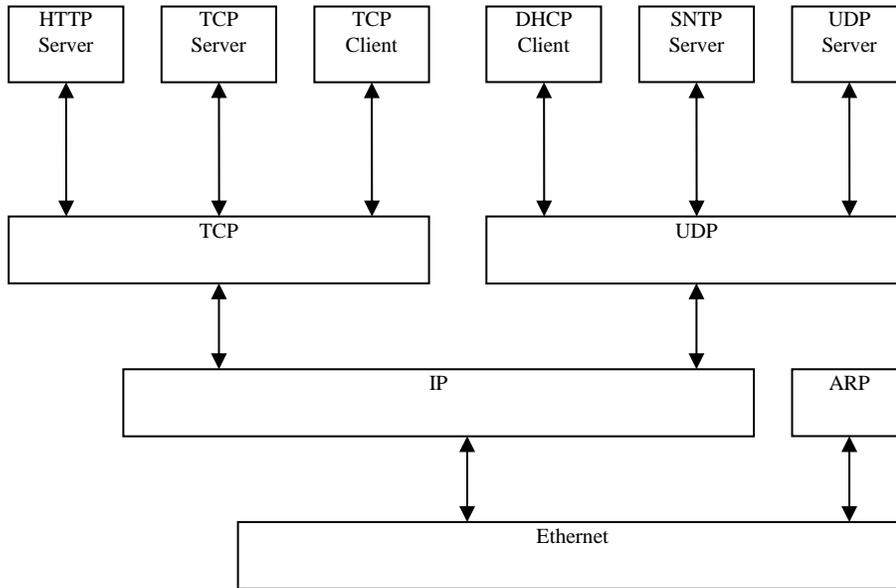
In order to test the applications, it was necessary to write test programs on the PC. I chose to write them in Delphi 7 due to its simplicity. Delphi 7 includes Indy components for Ethernet. The Serial Utility uses Async Professional for the serial interface.

## *Results*

The implementation using MikroE Libraries seem to work reasonably well. There are a few glitches that have not been resolved at this time. E.g. – TCP Client loses the ability to make a connection after some time. The only way to overcome this difficulty is to cycle power to the board.

I only wish that MikroE would publish the source code for the libraries which would make the job much easier. It would also facilitate debugging when a problem arises.

## *Internet Protocols Running in the Board*



**HTTP** server uses Port 80.

**TCP** server listens on Port 1234.

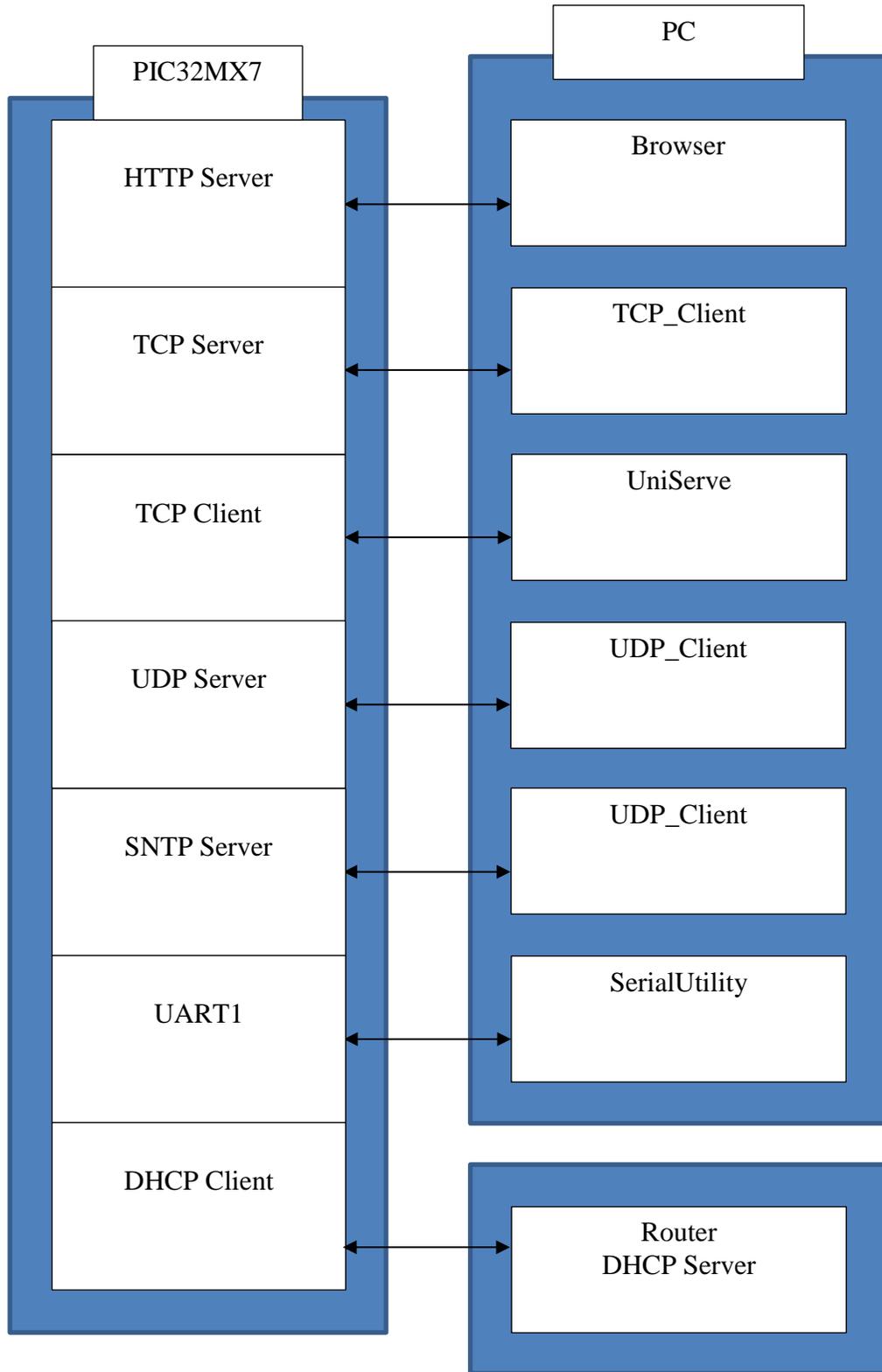
**TCP** client is used to push data to the TCP server (UniServe). UniServe is listening on Port 6000 and the client uses Port 6001.

**DHCP** uses Ports 67 and 68.

**SNTP** server uses Port 123 to listen for requests. Sends to remote Port as received.

**UDP** server listens Port 6060.

*Utilities for Testing the Software*



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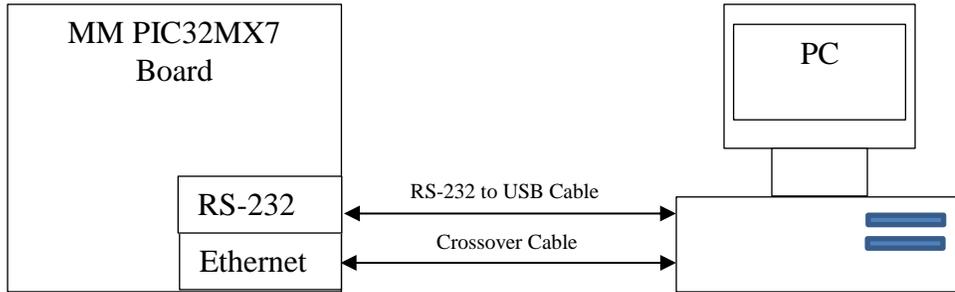
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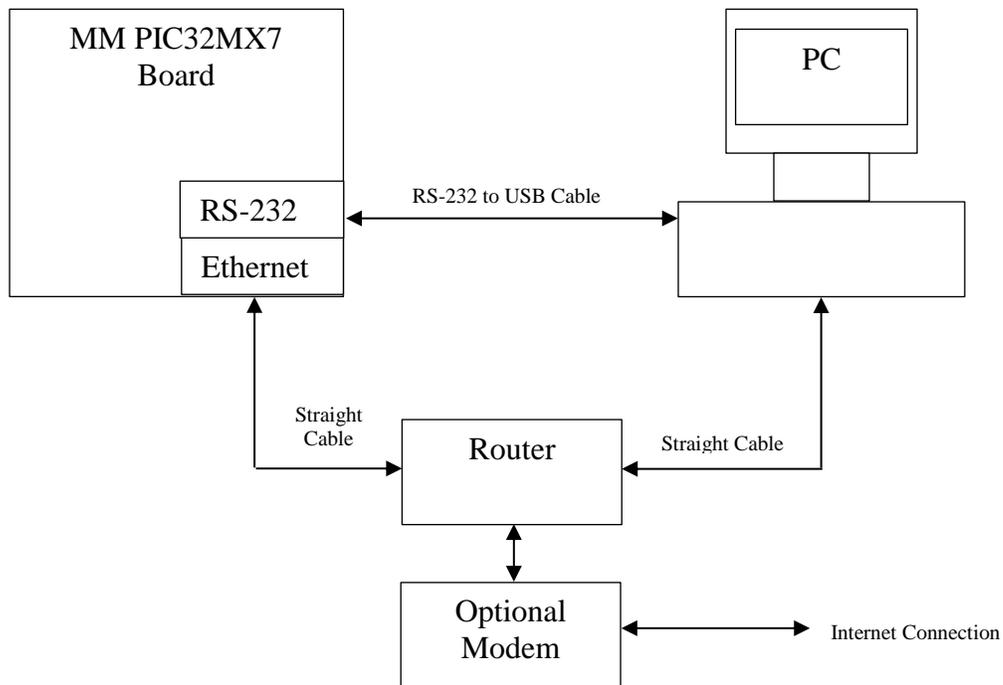
## *Hardware*

I have used 2 configurations. Both work equally well.

### **Direct Connection to PC**



### **Router**



## *Applications*

### **HTTP Server**

The HTTP Server application is the MikroE example from “Network\_Ethernet\_PIC32 Library”. I haven’t figured out how to compile a web page into resources.h yet so I can’t change the current web page.

### **TCP Server**

This is just a stub and will respond with “ACK” to a transmission from the TCP Client.

### **TCP Client**

This application has an input FIFO that will send data to the remote server (UniServe). UniServe saves the data to disk. It can service 8 connections simultaneously and sorts the data by creating folders with the client’s IP address. The file stored in the folder has today’s date for a file name. Right now a TCP “Push” event can be triggered by sending a ‘c’ command over the serial interface. In a real world application, the triggering event would be the closing of a switch or an A to D sample, etc.

### **UDP Server**

The UDP Server is just another form of the serial interface. It responds to commands from the Client.

### **SNTP Server**

This application is useful for providing time Synchronization over a local network. I have attempted to recreate the format documented in RFC4030 at <http://tools.ietf.org/html/rfc4330> but I am not sure if I was entirely successful.

### **Serial Utility for UART1**

This is an application that communicates with the serial interface. It is useful in debugging by sending out unsolicited information and status messages. It can also be used to trigger services in the micro. The debug messages have been left active. In real world applications these messages would be turned off using a compiler directive.

### **DHCP Client**

This application communicates with a Router to obtain an IP address for the local network. It can then rout messages to and from the Internet.

## *Timer*

This code uses the Core Timer available in PIC32MX7 to implement the clock keeping functions. It interrupts every millisecond to create a resolution of 1 millisecond.